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A Study on Lorentzian α -Sasakian Manifolds

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Abstract

The object of the present paper is to study the geometric properties of Concircular curvature tensor on Lorentzian α -Sasakian manifold admitting a type of quarter-symmetric metric connection. In the last, we provide an example of 3-dimensional Lorentzian α -Sasakian manifold endowed with the quarter-symmetric metric connection which is under consideration is an η -Einstein manifold with respect to the quarter-symmetric metric connection.

Keywords: Concircular curvature tensor; η -Einstein manifold; Lorentzian α -Sasakian manifold; Quarter-symmetric metric connection. 2010 Mathematics Subject Classification: 53C15; 53C26; 53C40.

1. Introduction

In 1975, Golab [5] defined and studied quarter-symmetric connection in differentiable manifolds. A linear connection $\overline{\nabla}$ on an *n*-dimensional Riemannian manifold (M,g) is said to be a quarter-symmetric connection [5] if its torsion tensor *T* defined by

$$T(X,Y) = \bar{\nabla}_X Y - \bar{\nabla}_Y X - [X,Y] \tag{1.1}$$

satisfies

$$T(X,Y) = \eta(Y)\phi X - \eta(X)\phi Y,$$
(1.2)

where ϕ is a (1,1) tensor field, η is a 1-form and *X*, *Y* are vector fields on $\Gamma(TM)$, $\Gamma(TM)$ is the set of all differentiable vector fields on *M*. In particular, if $\phi X = X$, then the quarter-symmetric connection reduces to the semi-symmetric connection [4]. Thus the notion of the quarter-symmetric connection generalizes the notion of the semi-symmetric connection. If moreover, a quarter-symmetric connection $\overline{\nabla}$ satisfies the condition

$$(\bar{\nabla}_X g)(Y, Z) = 0, \tag{1.3}$$

for all X, Y, Z on $\Gamma(TM)$, then $\overline{\nabla}$ is said to be a quarter-symmetric metric connection, otherwise it is said to be a quarter symmetric non-metric connection. Recently quarter-symmetric metric connection have been studied by several authors ([8], [9], [12]).

A differentiable manifold M is said to be a Lorentzian manifold, if M has a Lorentzian metric g, which is a symmetric non-degenerate (0,2) tensor field of index 1. Since the Lorentzian metric g is of index 1 therefore Lorentzian manifold M has not only spacelike vector fields but also lightlike and timelike vector fields. On a Lorentzian manifold this difference with Riemannian case gives interesting results. In 1989, K. Matsumoto used a structure vector field $-\xi$ instead of ξ in an almost para contact manifold and associated a Lorentzian metric with this resulting structure, called it as Lorentzian almost para contact manifold.

Yildiz and Murathan studied [15] Lorentzian α -Sasakian manifolds in 2005 and obtained results for conformally flat and quasi-conformally flat Lorentzian α -Sasakian manifolds. In 2009, Yildiz et al. ([16, 17]), further studied on three dimensional Lorentzian α -Sasakian manifolds and a class of Lorentzian α -Sasakian manifolds and obtained some important results. In 2013, U.C. De and K. De ([3]) studied on Lorentzian Trans-Sasakian manifolds, which is a generalization of Lorentzian α -Sasakian manifolds.

A concircular transformation ([7], [13]) on an *n*-dimensional Riemannian manifold M is a transformation under which every geodesic circle of M transforms into a geodesic circle. Every concircular transformation is always a conformal transformation [7]. Thus the concircular geometry, is a generalization of inversive geometry in the sense that the change of metric is more general than that induced by a circle

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preserving diffeomorphism (see also [2]). An interesting invariant of a concircular transformation is the concircular curvature tensor \bar{C} . It is defined by ([13], [14])

$$\bar{C}(X,Y)Z = \bar{R}(X,Y)Z - \frac{\bar{r}}{2n(2n+1)}[g(Y,Z)X - g(X,Z)Y].$$
(1.4)

for all vector fields $X, Y, Z \in \Gamma(TM)$, where \overline{R} and \overline{r} be the curvature tensor and scalar curvature with respect to the quarter-symmetric metric connection $\overline{\nabla}$ respectively.

Using (1.4), we obtain

$${}^{\circ}\bar{C}(X,Y,Z,W) = {}^{\circ}\bar{R}(X,Y,Z,W) - \frac{\bar{r}}{2n(2n+1)} [g(Y,Z)g(X,W) - g(X,Z)g(Y,W)],$$
(1.5)

where $(\bar{C}(X,Y,Z,W) = g(\bar{C}(X,Y)Z,W), (\bar{R}(X,Y,Z,W) = g(\bar{R}(X,Y)Z,W))$, where $X,Y,Z,W \in \Gamma(TM)$ and \bar{C} is the concircular curvature tensor and \bar{r} is the scalar curvature with respect to the quarter-symmetric metric connection respectively. Riemannian manifolds with vanishing concircular curvature tensor are of constant curvature. Thus the concircular curvature tensor is a measure of the failure of a Riemannian manifold to be of constant curvature.

In this paper, we study a type of quarter-symmetric metric connection on Lorentzian α -Sasakian manifolds. The paper is organized as follows: After introduction section two gives some prerequisites of a Lorentzian α -Sasakian manifold. In section three, we obtain a relation between the quarter-symmetric metric connection and Levi-civita connection. In section four, curvature tensor and Ricci tensor of Lorentzian α -Sasakian manifold with respect to quarter-symmetric metric connection are given. Section five is devoted to the study of ξ -concircularly flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric metric connection. Quasi-concircularly flat and ϕ -concircularly flat Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric metric connection have been studied in section six and seven respectively. In the next section, we study a Lorentzian α -Sasakian manifold satisfying $\overline{C} \cdot \overline{S} = 0$ with respect to a quarter-symmetric metric connection. In the last, we construct an example of a 3-dimensional Lorentzian α -Sasakian manifold endowed with the quarter-symmetric metric connection.

2. Preliminaries

An (2n+1)-dimensional differentiable manifold *M* is said to be a Lorentzian α -Sasakian manifold, if it admits a structure (ϕ, ξ, η, g) consisting of a (1,1) tensor field ϕ , vector field ξ , 1-form η and a Lorentzian metric *g* satisfying

$$\phi^2 X = X + \eta(X)\xi, \tag{2.1}$$

$$\phi \circ \xi = 0, \ \eta \circ \phi = 0, \ \eta(\xi) = -1, \ g(X,\xi) = \eta(X), \tag{2.2}$$

$$g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y), \tag{2.3}$$

$$(\nabla_X \phi) Y = \alpha \{ g(X, Y) \xi + \eta(Y) X \}$$
(2.4)

for any vector field X, Y on M, where ∇ denotes the covariant differentiation with respect to Lorentzian metric g. Also a Lorentzian α -Sasakian manifold satisfies [16]

$$\nabla_X \xi = \alpha \phi X, \tag{2.5}$$

$$(\nabla_X \eta) Y = \alpha_S(X, \phi Y) \tag{2.6}$$

for X, Y tangent to M.

Moreover, the curvature tensor *R*, the Ricci tensor *S* and the Ricci operator *Q* in a Lorentzian α -Sasakian manifold *M* with respect to the Levi-Civita connection ∇ , satisfies following relations [16]

$$R(\xi, X)Y = \alpha^2 \{ g(X, Y)\xi - \eta(Y)X \},$$
(2.7)

 $R(X,Y)\xi = \alpha^2 \{\eta(Y)X - \eta(X)Y\}, \qquad (2.8)$

 $R(\xi, X)\xi = -R(X,\xi)\xi = \alpha^{2} \{X + \eta(X)\xi\},$ (2.9)

$$S(X,\xi) = 2n\alpha^2 \eta(X), \qquad (2.10)$$

$$S(\xi,\xi) = -2n\alpha^2, \quad Q\xi = 2n\alpha^2\xi, \tag{2.11}$$

$$S(\phi X, \phi Y) = S(X, Y) - 2n\alpha^2 g(X, Y),$$

for all vector fields $X, Y \in \Gamma(TM).$ (2.12)

3. Relation Between the Quarter-Symmetric Metric Connection and Riemannian Connection

Let ∇ be a Riemannian connection and $\overline{\nabla}$ be a linear connection on Lorentzian α -Sasakian manifold M such that

$\bar{\nabla}_{X}Y = \nabla_{X}Y + H\left(X,Y\right),$	(3.1)
where <i>H</i> is a tensor of type $(1,2)$. Now if $\overline{\nabla}$ be a quarter-symmetric connection on <i>M</i> , then we have [5]	
$H(X,Y) = \frac{1}{2} [T(X,Y) + T'(X,Y) + T'(Y,X)],$	(3.2)
where	
$g\left(T'\left(X,Y\right),Z\right) = g\left(T\left(Z,X\right),Y\right).$	(3.3)
Using (1.2) in (3.3) , we get	
$T'(X,Y) = \eta(X)\phi Y - g(\phi X,Y)\xi.$	(3.4)
In view of (1.2) and (3.4) , equation (3.2) gives	
$H(X,Y) = \eta(Y)\phi X - g(\phi X,Y)\xi.$	(3.5)
Hence from (3.1), a quarter-symmetric connection $\overline{\nabla}$ on a Lorentzian α -Sasakian manifold <i>M</i> is given by	
$\bar{\nabla}_X Y = \nabla_X Y + \eta (Y) \phi X - g (\phi X, Y) \xi.$	(3.6)

Also we have

$$\left(\bar{\nabla}_{X}g\right)\left(Y,Z\right) = Xg(Y,Z) - g\left(\bar{\nabla}_{X}Y,Z\right) - g\left(Y,\bar{\nabla}_{X}Z\right)$$
(3.7)

With the help of (3.6), after simplification (3.7) gives

$$\left(\bar{\nabla}_{X}g\right)(Y,Z) = 0, \quad \forall Y,Z \in \Gamma(TM).$$
(3.8)

By virtue of (3.6) and (3.8), we conclude that $\overline{\nabla}$ is a quarter-symmetric metric connection. Therefore (3.6) is the relation between Riemannian connection and quarter-symmetric metric connection on a Lorentzian α -Sasakian manifold.

4. Curvature Tensor and Ricci Tensor of Lorentzian α -Sasakian Manifold with respect to the

Quarter-Symmetric Metric Connection

Let R(X,Y)Z and $\overline{R}(X,Y)Z$ be the curvature tensors of a Lorentzian α -Sasakian manifold M with respect to the Riemannian connection ∇ and quarter-symmetric metric connection $\overline{\nabla}$ respectively, then relation between R(X,Y)Z and $\overline{R}(X,Y)Z$ is given by

$$\bar{R}(X,Y)Z = R(X,Y)Z + \alpha \eta (Z) [\eta (Y)X - \eta (X)Y]$$

$$+ (2\alpha - 1) [g (\phi X, Z) \phi Y - g (\phi Y, Z) \phi X]$$

$$- \alpha [g(X,Z)\eta (Y) - g(Y,Z)\eta (X)]\xi.$$

$$(4.1)$$

From (4.1), we have

$$\bar{R}(\xi, X)Y = (\alpha^2 - \alpha)[g(X, Y)\xi - \eta(Y)X],$$
(4.2)

$$\bar{R}(X,Y)\xi = \left(\alpha^2 - \alpha\right)[\eta(Y)X - \eta(X)Y],\tag{4.3}$$

$$\bar{R}(\xi,Y)\xi = \left(\alpha^2 - \alpha\right)[Y + \eta(Y)\xi].$$
(4.4)

Let $\{e_1, e_2, \dots, e_{2n}, e_{2n+1} = \xi\}$ be a local orthonormal basis of vector fields in *M*. Since on a semi-Riemannian manifold, we have [10]

$$\sum_{i=1}^{2n+1} m{\epsilon}_i g(R(e_i,Y)Z,e_i) = S(Y,Z) \,, \ \sum_{i=1}^{2n+1} m{\epsilon}_i S(e_i,Y) g(e_i,Z) = S(Y,Z) \,,$$

$$\sum_{i=1}^{2n+1} \varepsilon_i g(e_i, Y) g(e_i, Z) = g(Y, Z),$$

and
$$\sum_{i=1}^{2n+1} \varepsilon_i g(\phi e_i, e_i) = trace(\phi),$$

where $\varepsilon_i = g(e_i, e_i), i = 1, 2, ..., 2n + 1$. Using above results on a Lorentzian α -Sasakian manifold, it can be easily verify that

$$\sum_{i=1}^{2n} g(R(e_i, Y)Z, e_i) = S(Y, Z) - \alpha^2 g(\phi Y, \phi Z),$$
(4.5)

$$\sum_{i=1}^{2n} S(e_i, Y)g(e_i, Z) = S(Y, Z) + 2n\alpha^2 \eta(Y) \eta(Z),$$
(4.6)

$$\sum_{i=1}^{2n} g(e_i, e_i) = 2n, \tag{4.7}$$

$$\sum_{i=1}^{2n} g(e_i, Y)g(e_i, Z) = g(\phi Y, \phi Z),$$
(4.8)

$$\sum_{i=1}^{2n} g(\phi e_i, e_i) = trace(\phi)$$
(4.9)

and

$$\sum_{i=1}^{2n} g(\bar{R}(e_i, Y)Z, e_i) = \bar{S}(Y, Z) - (\alpha^2 - \alpha) g(\phi Y, \phi Z).$$
(4.10)

Then from (4.1), we obtain

$$\bar{S}(Y,Z) = S(Y,Z) + \{(2n+1)\alpha - 1\} \eta(Y) \eta(Z)
+ (\alpha - 1)g(Y,Z) - (2\alpha - 1)trace(\phi)\Phi(Y,Z),$$
(4.11)

$$\bar{S}(Y,\xi) = 2n\left(\alpha^2 - \alpha\right)\eta\left(Y\right),\tag{4.12}$$

$$\bar{S}(\xi,\xi) = -2n\left(\alpha^2 - \alpha\right),\tag{4.13}$$

$$\bar{S}(\phi Y, \phi Z) = \bar{S}(Y, Z) - 2n\alpha^2 g(Y, Z) - 2n\alpha\eta(Y)\eta(Z).$$

$$\tag{4.14}$$

where \bar{S} and \bar{r} be the Ricci tensor and scalar curvature with respect to the quarter-symmetric metric connection $\bar{\nabla}$ respectively.

5. ξ -Concircularly Flat Lorentzian α -Sasakian Manifold with Respect to the Quarter-Symmetric Metric Connection

Definition 5.1. A Lorentzian α -Sasakian manifold is said to be ξ -concircularly flat [1] with respect to the quarter-symmetric metric connection if $\overline{C}(X,Y)\xi = 0$, where $X, Y \in \Gamma(TM)$.

Theorem 5.2. A Lorentzian α -Sasakian manifold admitting a quarter-symmetric metric connection $\overline{\nabla}$ is ξ -concircularly flat if and only if the scalar curvature \overline{r} with respect to the quarter-symmetric metric connection is equal to $2n(2n+1)(\alpha^2 - \alpha)$.

Proof. From (1.4), we have

$$\bar{C}(X,Y)\xi = \bar{R}(X,Y)\xi - \frac{\bar{r}}{2n(2n+1)}[\eta(Y)X - \eta(X)Y].$$
(5.1)

Using (4.3) in (5.1), we have

$$\bar{C}(X,Y)\xi = \left(\alpha^2 - \alpha\right) [\eta(Y)X - \eta(X)Y]$$

$$-\frac{\bar{r}}{2n(2n+1)} [\eta(Y)X - \eta(X)Y].$$
(5.2)

From (5.2), we have

$$\bar{C}(X,Y)\xi = \left[\left(\alpha^2 - \alpha\right) - \frac{\bar{r}}{2n(2n+1)}\right]\left[\eta\left(Y\right)X - \eta\left(X\right)Y\right].$$
(5.3)

Thus from (5.3), if $\bar{C}(X,Y)\xi = 0$, then $\bar{r} = 2n(2n+1)(\alpha^2 - \alpha)$ or $\eta(Y)X - \eta(X)Y = 0$, implies that $\eta(X) = 0$ which is not possible. Conversely, if $\bar{r} = 2n(2n+1)(\alpha^2 - \alpha)$, then from (5.3), it follows that $\bar{C}(X,Y)\xi = 0$. This completes the proof of the theorem.

6. Quasi-Concircularly Flat Lorentzian α-Sasakian Manifold with Respect to the Quarter-Symmetric

Metric Connection

Definition 6.1. A Lorentzian α -Sasakian manifold is said to be quasi-concircularly flat with respect to the quarter-symmetric metric connection if

$${}^{\mathbf{c}}\bar{\mathbf{C}}(\phi X, Y, Z, \phi W) = 0$$

$$(6.1)$$

where $X, Y, Z, W \in \Gamma(TM)$.

Definition 6.2. A Lorentzian α -Sasakian manifold is said to be an η -Einstein manifold [17] if its Ricci tensor S of the Levi-Civita connection is of the form

$$S(X,Y) = ag(X,Y) + b\eta(X)\eta(Y), \qquad (6.2)$$

where a and b are smooth functions on the manifold.

Theorem 6.3. If a Lorentzian α -Sasakian manifold admitting a quarter-symmetric metric connection is quasi-concircularly flat, then the manifold with respect to the quarter-symmetric metric connection is an η -Einstein manifold.

Proof. From (1.4), we have

$$\bar{C}(X,Y,Z,W) = {}^{*}\bar{R}(X,Y,Z,W) - \frac{\bar{r}}{2n(2n+1)} [g(Y,Z)g(X,W) - g(X,Z)g(Y,W)].$$
(6.3)

where ${}^{\circ}\bar{C}(X,Y,Z,W) = g(\bar{C}(X,Y)Z,W)$ and ${}^{\circ}\bar{R}(X,Y,Z,W) = g(\bar{R}(X,Y)Z,W)$. Now putting $X = \phi X$ and $W = \phi W$ in (6.3), we get

Using (6.1) in (6.4), we get

$${}^{\mathbf{k}}\bar{R}(\phi X, Y, Z, \phi W) = \frac{\bar{r}}{2n(2n+1)} [g(Y, Z)g(\phi X, \phi W) - g(\phi X, Z)g(Y, \phi W)].$$
(6.5)

Let $\{e_1, e_2, ..., e_{2n}, \xi\}$ be a local orthonormal basis of vector fields in M, then $\{\phi e_1, \phi e_2, ..., \phi e_{2n}, \xi\}$ is also a local orthonormal basis. Putting $X = W = e_i$ in (6.5) and summing over i = 1 to 2n, we obtain

$$\sum_{i=1}^{2n} \bar{R}(\phi e_i, Y, Z, \phi e_i) = \frac{\bar{r}}{2n(2n+1)} \sum_{i=1}^{2n} [g(Y, Z)g(\phi e_i, \phi e_i) - g(\phi e_i, Z)g(Y, \phi e_i)],$$
(6.6)

So by virtue of (2.3), (4.7), (4.8) and (4.10), the equation (6.6) takes the form

$$\bar{S}(Y,Z) = \left[\frac{\bar{r}(2n-1)}{2n(2n+1)} + \left(\alpha^2 - \alpha\right)\right]g(Y,Z) - \left[\frac{\bar{r}}{2n(2n+1)} - \left(\alpha^2 - \alpha\right)\right]\eta(Y)\eta(Z).$$
(6.7)

 $\bar{S}(Y,Z) = ag(Y,Z) + b\eta(Y)\eta(Z),$

where
$$a = \left[\frac{\bar{r}(2n-1)}{2n(2n+1)} + (\alpha^2 - \alpha)\right]$$
 and $b = -\left[\frac{\bar{r}}{2n(2n+1)} - (\alpha^2 - \alpha)\right]$

From which it follows that the manifold is an η -Einstein manifold with respect to the quarter-symmetric metric connection. This completes the proof of the theorem.

7. ϕ -Concircularly Flat Lorentzian α -Sasakian Manifold with Respect to the Quarter-Symmetric Metric Connection

Definition 7.1. A Lorentzian α -Sasakian manifold is said to be ϕ -concircularly flat [11] with respect to the quarter-symmetric metric connection if

$$\dot{C}(\phi X, \phi Y, \phi Z, \phi W) = 0,$$

where $X, Y, Z, W \in \Gamma(TM)$.

Theorem 7.2. If a Lorentzian α -Sasakian manifold admitting a quarter-symmetric metric connection is ϕ -concircularly flat, then the manifold with respect to the quarter-symmetric metric connection is an η -Einstein manifold.

Proof. From (1.4), we have

where ${}^{\circ}\bar{C}(X,Y,Z,W) = g(\bar{C}(X,Y)Z,W)$ and ${}^{\circ}\bar{R}(X,Y,Z,W) = g(\bar{R}(X,Y)Z,W)$. Now putting $X = \phi X$, $Y = \phi Y$, $Z = \phi Z$, $W = \phi W$ in (7.2), we get

Using (7.1) in (7.3), we get

$${}^{\mathbf{k}}\bar{R}(\phi X,\phi Y,\phi Z,\phi W) = \frac{\bar{r}}{2n(2n+1)} [g(\phi Y,\phi Z)g(\phi X,\phi W) - g(\phi X,\phi Z)g(\phi Y,\phi W)].$$

$$\tag{7.4}$$

Let $\{e_1, e_2, ..., e_{2n}, \xi\}$ be a local orthonormal basis of vector fields in M, then $\{\phi e_1, \phi e_2, ..., \phi e_{2n}, \xi\}$ is also a local orthonormal basis. Putting $X = W = e_i$ in (7.4) and summing over i = 1 to 2n, we obtain

$$\sum_{i=1}^{2n} \bar{R}(\phi e_i, \phi Y, \phi Z, \phi e_i) = \frac{\bar{r}}{2n(2n+1)} \sum_{i=1}^{2n} [g(\phi Y, \phi Z)g(\phi e_i, \phi e_i) - g(\phi e_i, \phi Z)g(\phi Y, \phi e_i)],$$
(7.5)

So by virtue of (4.7), (4.8) and (4.10), the equation (7.5) takes the form

$$\bar{S}(\phi Y, \phi Z) = \left[\frac{\bar{r}(2n-1)}{2n(2n+1)} + \left(\alpha^2 - \alpha\right)\right]g(\phi Y, \phi Z).$$
(7.6)

By making use of (2.3) and (4.14) in equation (7.6), we obtain

$$\bar{S}(Y,Z) = \left[\frac{\bar{r}(2n-1)}{2n(2n+1)} + (\alpha^2 - \alpha) + 2n\alpha^2\right]g(Y,Z) + \left[\frac{\bar{r}(2n-1)}{2n(2n+1)} + (\alpha^2 - \alpha) + 2n\alpha\right]\eta(Y)\eta(Z),$$
(7.7)

or

 $\bar{S}(Y,Z) = ag(Y,Z) + b\eta(Y)\eta(Z),$

where
$$a = \left[\frac{\bar{r}(2n-1)}{2n(2n+1)} + (\alpha^2 - \alpha) + 2n\alpha^2\right]$$
 and $b = \left[\frac{\bar{r}(2n-1)}{2n(2n+1)} + (\alpha^2 - \alpha) + 2n\alpha\right]$.

From which it follows that the manifold is an η -Einstein manifold with respect to the quarter-symmetric metric connection. This completes the proof of the theorem.

8. Lorentzian α -Sasakian Manifold Satisfying $\overline{C} \cdot \overline{S} = 0$ with Respect to the Quarter-Symmetric Metric Connection

Definition 8.1. A Lorentzian α -Sasakian manifold is said to be an Einstein manifold if its Ricci tensor S of the Levi-Civita connection is of the form

$$S(X,Y) = ag(X,Y), \tag{8.1}$$

where a is a constant on the manifold.

Theorem 8.2. If Lorentzian α -Sasakian manifold satisfying $\overline{C} \cdot \overline{S} = 0$ with respect to a quarter-symmetric metric connection, then the manifold is an Einstein manifold with respect to the quarter-symmetric metric connection.

(7.1)

Proof. We consider Lorentzian α -Sasakian manifolds with respect to a quarter-symmetric metric connection $\overline{\nabla}$ satisfying the curvature condition $\overline{C} \cdot \overline{S} = 0$. Then

$$\left(\bar{C}\left(X,Y\right)\cdot\bar{S}\right)\left(Z,W\right)=0.$$
(8.2)

So,

$$\bar{S}(\bar{C}(X,Y)Z,W) + \bar{S}(Z,\bar{C}(X,Y)W) = 0.$$

$$(8.3)$$

Putting $X = \xi$ in (8.3), we get

$$\bar{S}(\bar{C}(\xi,Y)Z,W) + \bar{S}(Z,\bar{C}(\xi,Y)W) = 0.$$

$$(8.4)$$

From equation (1.4), we have

$$\bar{C}(\xi,Y)Z = \bar{R}(\xi,Y)Z - \frac{\bar{r}}{2n(2n+1)}[g(Y,Z)\xi - \eta(Z)Y].$$
(8.5)

Using (4.2) in the equation (8.5), we obtain

$$\bar{C}(\xi, Y)Z = \{\alpha^2 - \alpha - \frac{\bar{r}}{2n(2n+1)}\}[g(Y, Z)\xi - \eta(Z)Y].$$
(8.6)

Using (8.6) and putting $Z = \xi$ in (8.4) and using the equations (2.2), (4.12), we obtain

$$\{\alpha^2 - \alpha - \frac{r}{2n(2n+1)}\}[\bar{S}(Y,W) - 2n(\alpha^2 - \alpha)g(Y,W)] = 0.$$
(8.7)

Therefore,

 $\bar{S}(Y,W) = 2n(\alpha^2 - \alpha)g(Y,W)$

provided $\bar{r} \neq 2n(2n+1)(\alpha^2 - \alpha)$.

This means that the manifold is an Einstein manifold with respect to the quarter-symmetric metric connection. This completes the proof.

9. Example

In this section we construct an example on Lorentzian α -Sasakian manifold endowed with the quarter-symmetric metric connection. We consider the 3-dimensional manifold $M^3 = \{(x, y, z) : x, y, z \in \mathbb{R}\}$, where (x, y, z) are the standard coordinates in \mathbb{R}^3 . We choose the vector fields

$$e_1 = e^z \frac{\partial}{\partial y}, \ e_2 = e^z (\frac{\partial}{\partial x} + \frac{\partial}{\partial y}), \ e_3 = \alpha \frac{\partial}{\partial z} = \xi,$$

which are linearly independent at each point of M^3 . Let g be a Lorentzian metric defined by

$$g(e_1, e_1) = 1, \ g(e_2, e_2) = 1, \ g(e_3, e_3) = -1,$$

and $g(e_i, e_j) = 0$ if $i \neq j$. Let ϕ be the (1, 1)-tensor field defined by

$$\phi e_1 = -e_1, \ \phi e_2 = -e_2, \ \phi e_3 = 0.$$

and η be a 1-form defined by $\eta(X) = g(X, e_3)$ for any $X \in \Gamma(TM^3)$ Now using the linearity of ϕ and g, we obtain

$$\phi^2 X = X + \eta(X)\xi,$$

 $\eta(\xi) = -1,$

and

$$g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y),$$

for any vector fields $X, Y \in \Gamma(TM^3)$. Thus for $e_3 = \xi$, the structure (ϕ, ξ, η, g) defines a Lorentzian para-contact metric structure on M^3 . Now, we have

$$[e_1, e_2] = 0, \ [e_2, e_3] = -\alpha e_2, \ [e_1, e_3] = -\alpha e_1,$$

Let ∇ be the Levi-Civita connection of the Lorentzian metric g which is given by Koszul's formula defined by

$$2g(\nabla_X Y, Z) = Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) - g(X, [Y, Z]) - g(Y, [X, Z]) + g(Z, [X, Y]).$$

Using Koszul's formula, we obtain the following:

$$\begin{aligned} \nabla_{e_1} e_1 &= -\alpha e_3, \ \nabla_{e_1} e_2 &= 0, \ \nabla_{e_1} e_3 &= -\alpha e_1, \\ \nabla_{e_2} e_1 &= 0, \ \nabla_{e_2} e_2 &= -\alpha e_3, \ \nabla_{e_2} e_3 &= -\alpha e_2, \\ \nabla_{e_3} e_1 &= 0, \ \nabla_{e_3} e_2 &= 0, \ \nabla_{e_3} e_3 &= 0, \end{aligned} \tag{9.1}$$

In view of the above results, we see that

$$(\nabla_X \eta) Y = \alpha g(\phi X, Y) \xi,$$

 $\nabla_X \xi = \alpha \phi X,$

for all $X, Y \in \Gamma(TM^3)$ and $\xi = e_3$. Therefore the manifold is a Lorentzian α -Sasakian manifold with the structure (ϕ, ξ, η, g) . It is known that

$$R(X,Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z$$

Now using (9.1), we can easily obtain the non-zero components of the curvature tensor *R* as follows:

$$R(e_{1},e_{2})e_{1} = -\alpha^{2}e_{2}, R(e_{1},e_{2})e_{2} = \alpha^{2}e_{1},$$

$$R(e_{1},e_{3})e_{1} = -\alpha^{2}e_{3}, R(e_{1},e_{3})e_{3} = -\alpha^{2}e_{1}$$

$$R(e_{2},e_{3})e_{2} = -\alpha^{2}e_{3}, R(e_{2},e_{3})e_{3} = -\alpha^{2}e_{2},$$
(9.2)

Let X, Y and Z be any three vector fields given by

$$X = X^{1}e_{1} + X^{2}e_{2} + X^{3}e_{3},$$

$$Y = Y^{1}e_{1} + Y^{2}e_{2} + Y^{3}e_{3},$$

$$Z = Z^{1}e_{1} + Z^{2}e_{2} + Z^{3}e_{3}$$
(9.3)

where X^i, Y^i and Z^i , for all i = 1, 2, 3 are all non-zero real numbers. Then

$$R(X,Y)Z = R(X^{1}e_{1} + X^{2}e_{2} + X^{3}e_{3}, Y^{1}e_{1} + Y^{2}e_{2} + Y^{3}e)(Z^{1}e_{1} + Z^{2}e_{2} + Z^{3}e_{3}).$$
(9.4)

Using equation (9.2) in (9.4), we get

$$R(X,Y)Z = \alpha^2 \{g(Y,Z)X - g(X,Z)Y\}.$$
(9.5)

Hence, the 3-dimensional Lorentzian α -Sasakian manifold is of constant curvature α^2 . Also from (9.5), we obtain

$$S(Y,Z) = 2\alpha^2 g(Y,Z) \tag{9.6}$$

which gives $S(e_1, e_1) = S(e_2, e_2) = 2\alpha^2$, $S(e_3, e_3) = -2\alpha^2$ and therefore the scalar curvature $r = 6\alpha^2$. Now using (9.1) in (3.7), we obtain the components of quarter-symmetric metric connection $\bar{\nabla}$ as follows:

$$\begin{aligned} \nabla_{e_1} e_1 &= -(\alpha - 1)e_3, \ \nabla_{e_1} e_2 &= 0, \ \nabla_{e_1} e_3 = -(\alpha - 1)e_1, \\ \bar{\nabla}_{e_2} e_1 &= 0, \ \bar{\nabla}_{e_2} e_2 &= -(\alpha - 1)e_3, \ \bar{\nabla}_{e_2} e_3 &= -(\alpha - 1)e_2, \\ \bar{\nabla}_{e_3} e_1 &= 0, \quad \bar{\nabla}_{e_3} e_2 &= 0, \quad \bar{\nabla}_{e_3} e_3 &= 0, \end{aligned}$$

$$(9.7)$$

Using above results, we can easily obtain the components of curvature tensor \bar{R} with respect to quarter–symmetric metric connection $\bar{\nabla}$ as follows:

$$\bar{R}(e_1, e_2)e_1 = -(\alpha - 1)^2 e_2, \ \bar{R}(e_1, e_2)e_2 = (\alpha - 1)^2 e_1, \ \bar{R}(e_1, e_2)e_3 = 0,$$

$$\bar{R}(e_1, e_3)e_1 = -\alpha(\alpha - 1)e_3, \ \bar{R}(e_1, e_3)e_2 = 0, \ \bar{R}(e_1, e_3)e_3 = -\alpha(\alpha - 1)e_1$$

$$\bar{R}(e_2, e_3)e_1 = 0, \ \bar{R}(e_2, e_3)e_2 = -\alpha(\alpha - 1)e_3, \ \bar{R}(e_2, e_3)e_3 = -\alpha(\alpha - 1)e_2,$$
(9.8)

With the help of (9.8), we find the Ricci tensors \bar{S} with respect to the quarter-symmetric metric connection as:

 $\bar{S}(e_1, e_1) = \bar{S}(e_2, e_2) = (2\alpha - 1)(\alpha - 1), \ \bar{S}(e_3, e_3) = -2\alpha(\alpha - 1).$

From above results, it follows that the scalar curvature tensor with respect to the quarter-symmetric metric connection is $\bar{r} = 2(3\alpha - 1)(\alpha - 1)$.

Using (4.11) and (9.6) in 3-dimensional Lorentzian α -Sasakian manifold M^3 , we have

$$\bar{S}(Y,Z) = (2\alpha - 1)(\alpha - 1)g(Y,Z) - (\alpha - 1)\eta(Y)\eta(Z).$$

Thus the three dimensional Lorentzian α -Sasakian manifold M^3 is an η -Einstein manifold with respect to the quarter-symmetric metric connection $\overline{\nabla}$.

If we take $\alpha = 1$ in this example, then 3-dimensional Lorentzian α -Sasakian manifold M^3 becomes flat with respect to the quarter-symmetric metric connection $\overline{\nabla}$.

332

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